

INTRODUCTION

Analyzing EHR (electronic health record) data allows us to improve clinical decision support and predict clinical processes for specific conditions. Nevertheless, time-series EHR data are always incomplete and irregularly sampled.

The topic of this paper is applications of neural ODE in deep learning models (e.g., recurrent neural networks or RNNs) based on irregularly-sampled time series EHR data. Figure 1 shows the main topics of the 16 articles reviewed including the baseline model neural ODE from Chen et al. (2018) and how they related to each other.

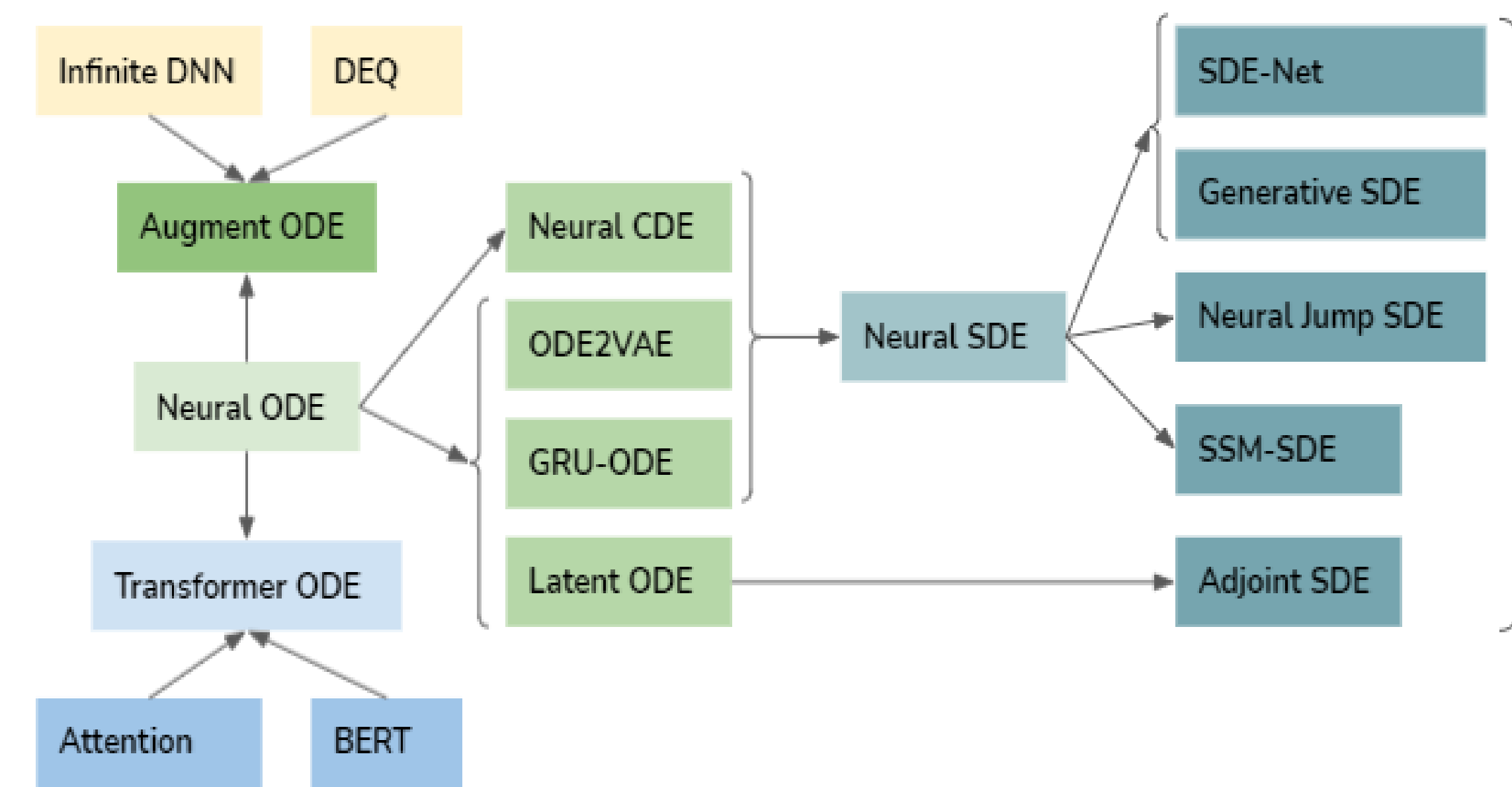


Figure 1: How ODE-based models related to the neural ODE model and also how they are related to each other

METHOD

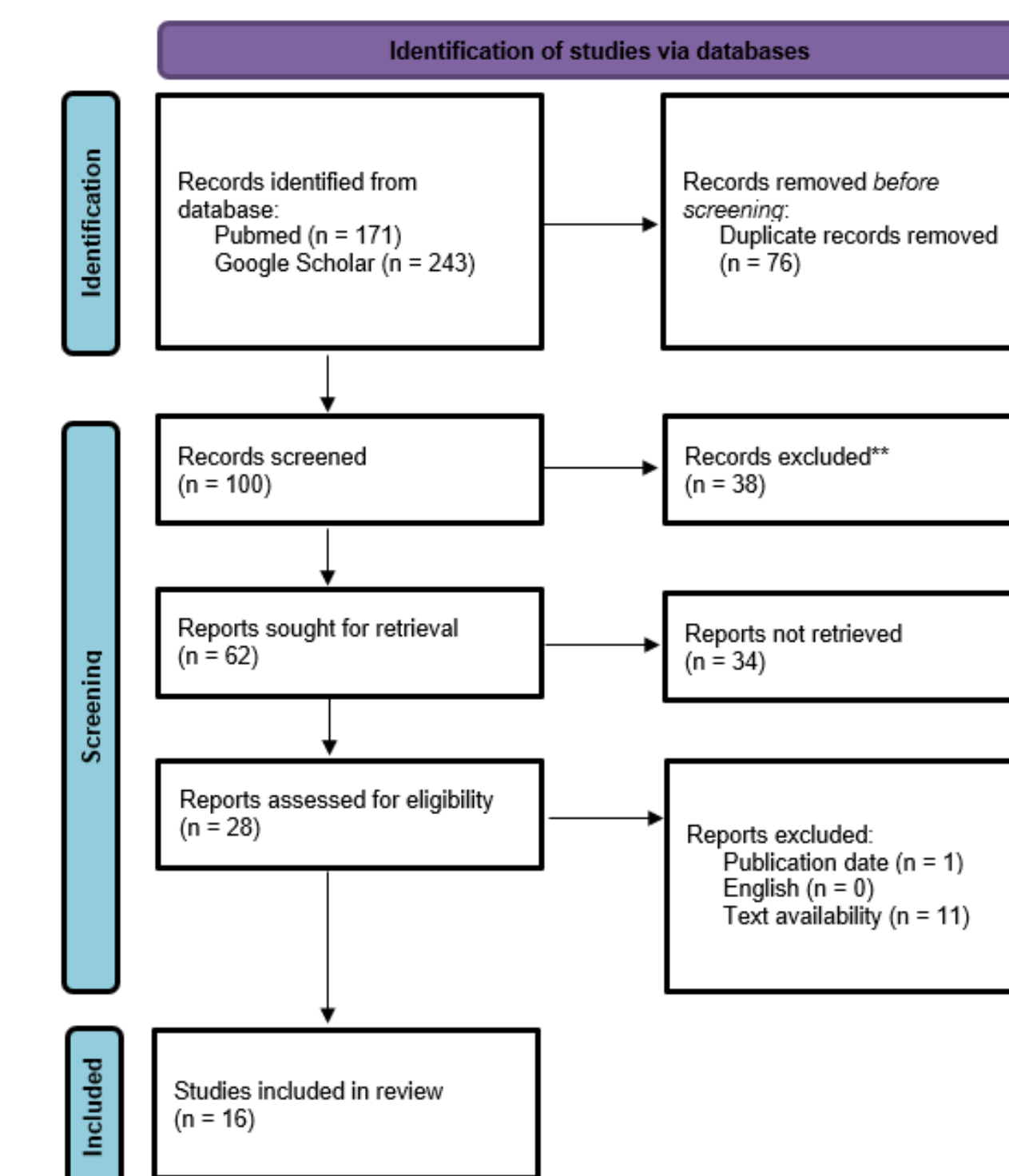


Figure 2: The PRISMA diagram

CONCLUSION

The current focus of my research is to develop deep learning models that take time-series data from EHRs and predict drug concentrations based on it, in which the concentration distribution of the drug itself conforms to an ODE.

Considering the specific data for my project, it is not necessary to utilize SDE-based methods. The latent ODE solves the problem from the nature of the ODE, it seems worthwhile to use it when the dataset is not too large. Alternatively, a neural CDE model can be employed, which smooths out the trajectory of the hidden state by using a natural cubic spline. As well, augmented ODEs may eventually replace traditional neural ODEs.

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SUMMARY & DISCUSSION

Table 1: Summary of models

Type	Summary	Description	Future study
Neural ODE	Baseline model.	Updates hidden states continuously, but the model's trajectory cannot be adjusted based on observations.	Add uncertainty into the trajectory (ODE-related models); add random noise to fit real-world data (SDE-related models).
ODE-related	Neural CDE	Could smooth the invisible trajectory.	The <u>latent ODE</u> and the <u>neural CDE</u> have outperformed other models based on neural ODEs. It is essential to utilize latent ODEs on datasets that are not particularly large, despite their higher computational complexity and ability to lead to optimal hyperparameter determination. There are the same limitations of the neural CDE as that of the potential ODE: lower speed and more parameters.
	ODE2VAE (Variational autoencoder)	Is a latent second-order ODE model for high-dimensional sequential data.	
	GRU-ODE (Gated recurrent units)	Is the continuous-time version of the GRU.	
	Latent ODE	Can naturally handle arbitrary time gaps between observations.	
SDE-related (Stochastic differential equation)	SDE-Net	A new method for quantifying uncertainties of DNNs (deep neural networks) from a dynamical system perspective.	Most SDE-related models are not “real” SDE, so the best model should be the <u>adjoint SDE</u> . When comparing the potential SDE model to the potential ODE model when using the same data set, Li et al. (2020) report that the test MSE (Mean square error) of the possible SDE model is slightly lower. It is difficult to determine under what circumstances neural SDE models will be more effective than neural ODE models because SDE models are more complex, memory, and time-intensive.
	Generative SDE	Uses numerical SDE solvers to generate samples.	
	Neural Jump SDE	Provides a data-driven approach to learn continuous and discrete dynamic behavior.	
	SSM-SDE (State space model)	A new model of insulin-glucose dynamics for forecasting blood glucose in type 1 diabetics.	
	Adjoint SDE	Allows time-efficient and constant-memory computation of gradients with high-order adaptive solvers.	
Other	Augment ODE	There exist functions that neural ODE cannot represent. Augmented ODEs are more expressive and stable models.	Eventually, augmented ODEs could replace traditional neural ODEs.
	Transformer ODE	Neural ODEs are typically defined using vector fields parameterized via Lipschitz networks. The authors (Kim et al., 2021) investigated the Lipschitz constant of self-attention.	As of yet, there is no literature linking the transformer-related model with the neural ODE network.